

Global solutions for a hyperbolic model of multiphase flow

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joint work with

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Introduction

We consider a hyperbolic model for 1–D multiphase reactive flow

$$\begin{cases} v_t - u_x & = 0 \\ u_t + p(v, \lambda)_x & = 0 \\ \lambda_t & = \frac{\alpha}{\tau}(p - p_e)\lambda(\lambda - 1) \end{cases}$$

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 λ : mass density fraction of vapor in the fluid

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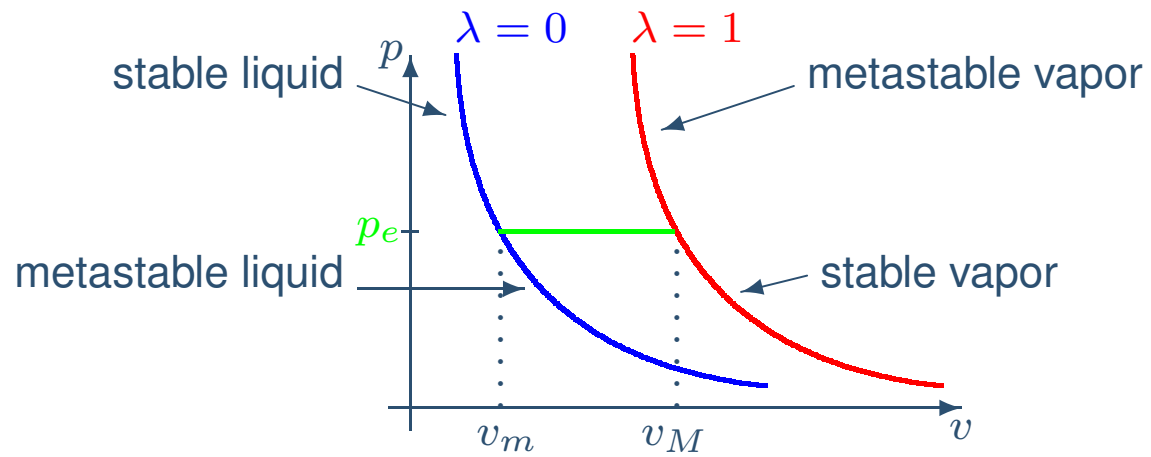
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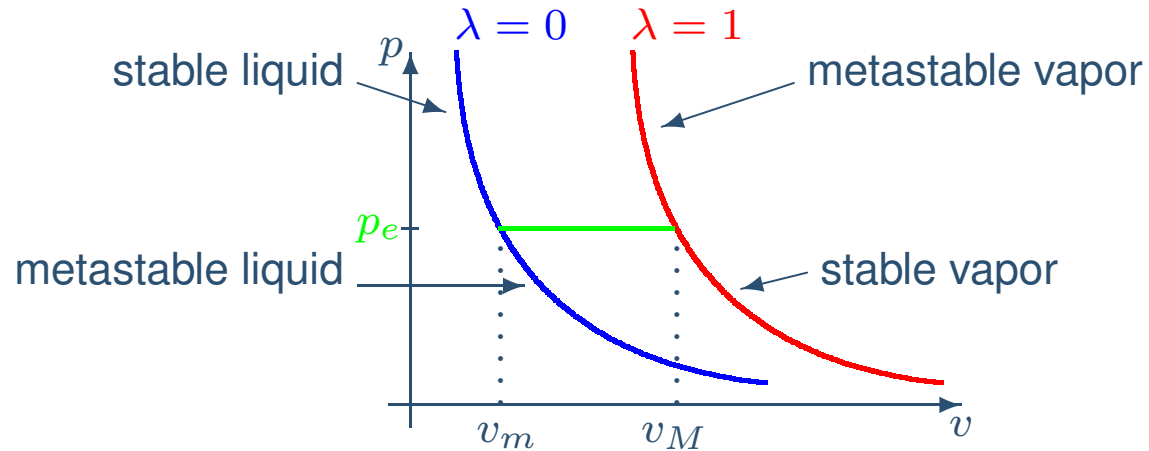
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[Fan, *SIAM J. Appl. Math.* 2000]

The model



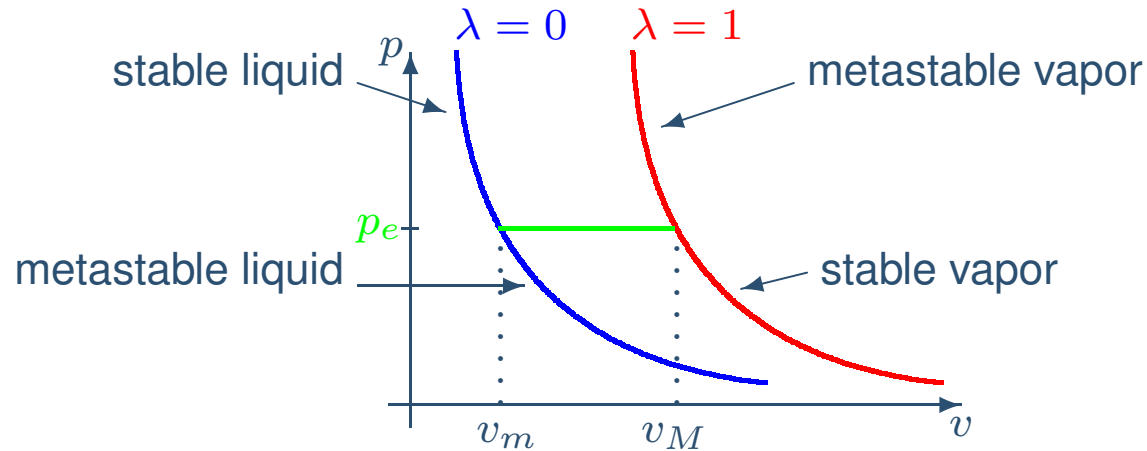
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The model may take into account viscosity terms

$$\begin{cases} v_t - u_x & = 0 \\ u_t + p_x & = \varepsilon u_{xx} \\ \lambda_t & = \frac{\alpha}{\tau} (p - p_e) \lambda (\lambda - 1) + b \varepsilon \lambda_{xx} \end{cases}$$

Riemann problem for the 0-viscosity and 0-relaxation limit: [Corli and Fan, 2005].

Aim of this work

- For a fixed relaxation time $\tau > 0$, look for **global (in time) solutions** of the Cauchy problem with **large BV data**

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- ◆ the **homogeneous system**: the 3×3 system of conservation laws

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We first focus on the analysis of system **(H)**.

Comparison with another model

In Eulerian coordinates, for $p = a^2(\lambda)\rho$ and $\rho = 1/v$, the system rewrites as

$$\begin{cases} \rho_t + (\rho u)_x & = 0, \\ (\rho u)_t + (\rho u^2 + p(\rho, \lambda))_x & = 0, \\ (\rho \lambda)_t + (\rho \lambda u)_x & = 0. \end{cases}$$

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In [Benzoni-Gavage, 1991] many models for diphasic flows are proposed, for instance

$$\begin{cases} (\rho_l R_l)_t + (\rho_l R_l u_l)_x & = 0 \\ (\rho_g R_g)_t + (\rho_g R_g u_g)_x & = 0 \\ (\rho_l R_l u_l + \rho_g R_g u_g)_t + (\rho_l R_l u_l^2 + \rho_g R_g u_g^2 + p)_x & = 0. \end{cases}$$

Here l and g stand for *liquid* and *gas*; ρ_l , R_l , u_l are the liquid density, phase fraction, velocity, and analogously for the gas, $R_l + R_g = 1$, $p = a^2 \rho_g$.

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If $u_l = u_g$ and $\rho_l = 1$, define the concentration $c = \frac{\rho_g R_g}{\rho_l R_l}$ then [Peng, 1994]

$$\begin{cases} (R_l)_t + (R_l u)_x & = 0 \\ (R_l c)_t + (R_l c u)_x & = 0 \\ (R_l(1+c)u)_t + (R_l(1+c)u^2 + p)_x & = 0 \end{cases} \quad \text{(P)}$$

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System **(P)** is analogous to **(H)** in Eulerian coordinates, with $\lambda = \frac{c}{1+c}$, but the pressure laws differ when $\lambda, c \sim 0$.

The homogeneous system

Issue: existence of **weak solutions** (in the BV class) for the Cauchy problem, **globally defined in time**, with possibly **large data**:

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$$\lambda = \lambda_o(x)$$

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■ For **small** BV data: well-posedness of the Cauchy problem.

[Glimm 1965; Bressan, *Hyperbolic systems...*, 2000].

Known results (partial list)

- If λ_o is constant: the Cauchy problem for $v_t - u_x = 0$, $u_t + (a^2/v)_x = 0$ has a global solution for every initial data (v_o, u_o) with

$$\text{Tot.Var. } (v_o, u_o) < \infty$$

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See also [Holden, Risebro & Sande (2008)].

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- For the full Euler system: Liu (1977), Temple (1981).

Other known results

About p -system with $\gamma = 1$ and source term:

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- [Luo-Natalini-Yang 2000], [Amadori-Guerra, 2001]:
global existence of BV solutions for

$$\begin{cases} v_t - u_x & = 0 \\ u_t + (1/v)_x & = \frac{1}{\tau} r(v, u), \end{cases}$$

and relaxation limit for $\tau \rightarrow 0$. Typical case: $r(v, u) = A(v) - u$.

Main result for the homogeneous system

Assume: $v_o(x) \geq \underline{v} > 0$, $\lambda_o(x) \in [0, 1]$ and define

$$A_o = 2 \sup \sum_{j=1}^n \frac{|a(\lambda(x_j)) - a(\lambda(x_{j-1}))|}{a(\lambda(x_j)) + a(\lambda(x_{j-1}))}.$$

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Theorem 1: For a suitable decreasing function $H : (0, 1/2] \rightarrow [0, \infty)$, if

$$A_o < \frac{1}{2},$$

$$\text{Tot.Var.} (\log p_o) + \frac{1}{\inf a_o} \text{Tot.Var.} u_o < H(A_o),$$

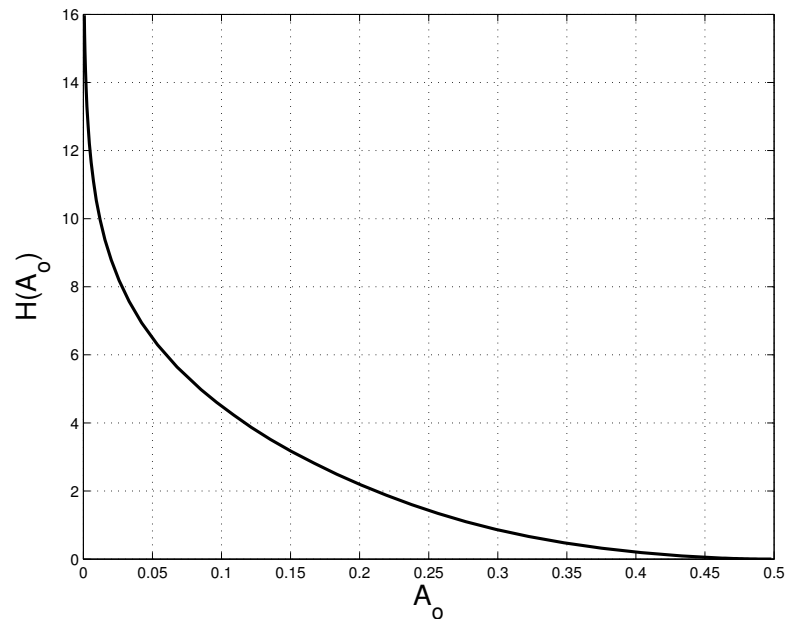
then the Cauchy problem for **(H)** has a weak entropic solution (v, u, λ) defined for $t \geq 0$, with uniformly bounded total variation.

The function H can be explicitly computed. It satisfies

$$H : (0, 1/2] \rightarrow [0, \infty), \quad H(1/2) = 0, \quad \lim_{A \rightarrow 0^+} H(A) = +\infty.$$

Note that: the smaller is A_o , the larger is $H(A_o)$ (recall Nishida-Smoller).

Graph of $H(A_o)$:

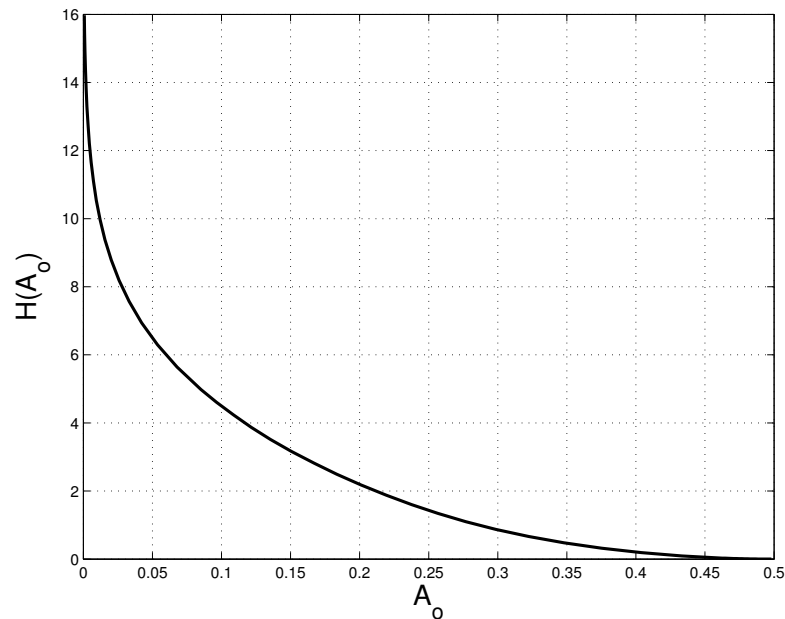


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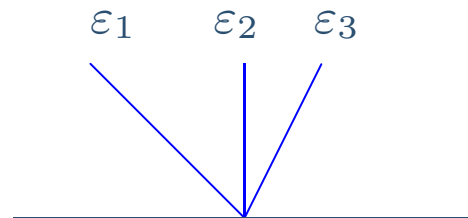
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The Riemann problem

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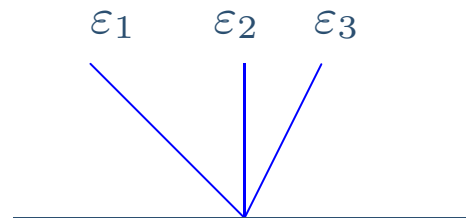


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- Phase waves are stationary: p, u are conserved across them (a “kinetic condition”).

$$\begin{array}{|l} p_\ell = p_r \\ u_\ell = u_r \end{array}$$

- Strength of the 1-, 3- waves:

$$|\varepsilon_{1,3}| = \frac{1}{2} \left| \log \left(\frac{v_r}{v_\ell} \right) \right| = \frac{1}{2} \left| \log \left(\frac{p_r}{p_\ell} \right) \right| .$$

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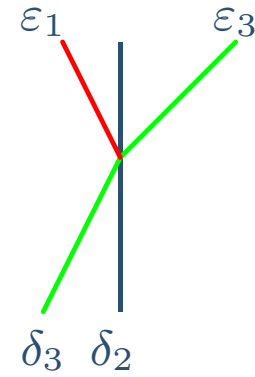
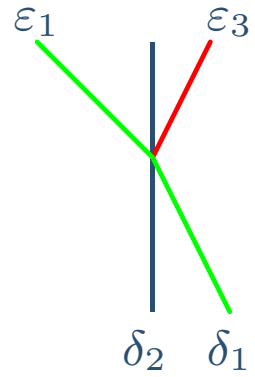
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Interactions with phase waves



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Lemma:

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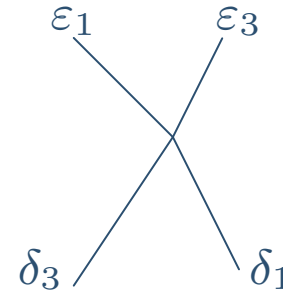
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- The reflected wave may be very large.
- The variation $|\varepsilon_1| + |\varepsilon_3| - |\delta_i|$ may increase iff δ_i is moving toward a more liquid region.

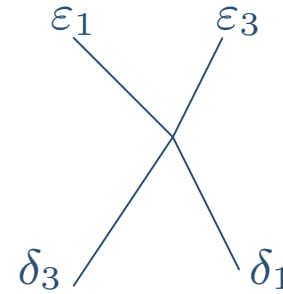
Interactions of sonic waves – 1

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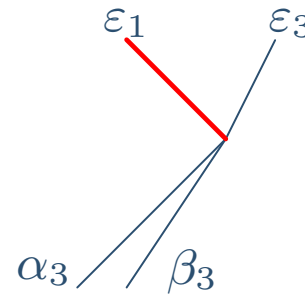
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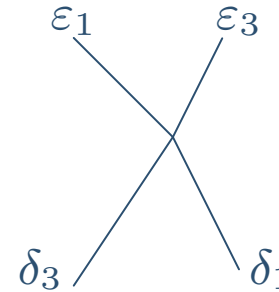
- Waves of the same family:

$$|\varepsilon_1| + |\varepsilon_3| \leq |\alpha_3| + |\beta_3|$$



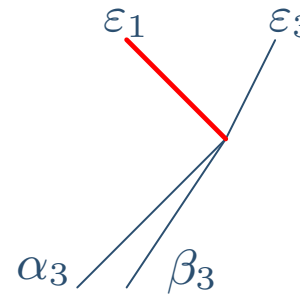
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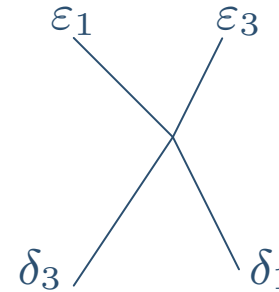
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⇒ If λ is constant (no 2-waves are present), then $L(t) = \sum_{i=1,3} |\varepsilon_i|$ is not increasing [Nishida 68].

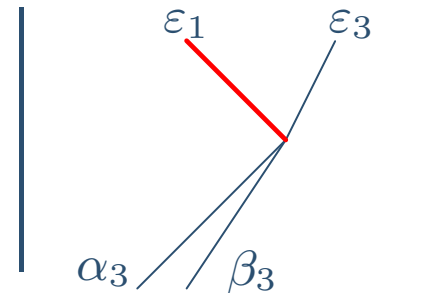
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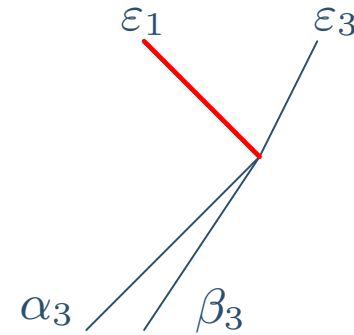
However, large reflected waves may interact with phase waves, producing even larger waves...

⇒ **Needed:** improved estimates on the **reflected waves**.

Interactions of sonic waves – 2

Lemma: Let two waves of the same family, of sizes α_i and β_i ($i = 1, 3$) interact, producing $\varepsilon_1, \varepsilon_3$; assume that for $m > 0$

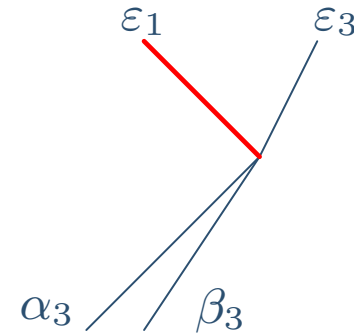
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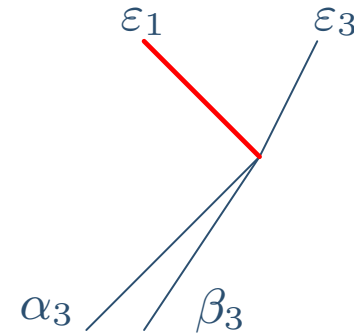
Then there exists a damping coefficient $d = d(m)$, with $0 < d(m) < 1$, s.t.

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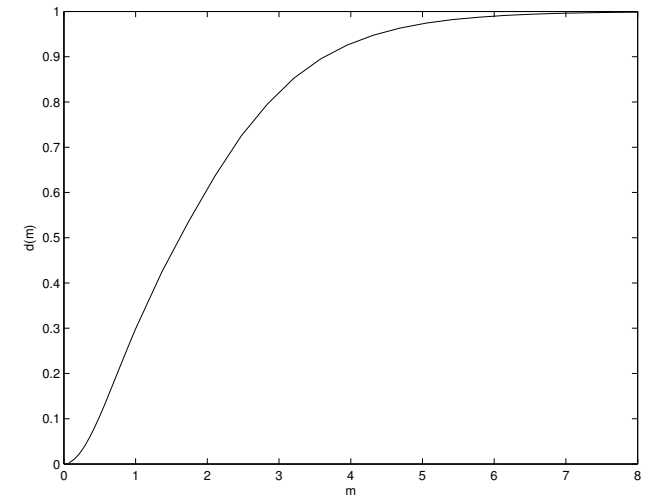
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Note: $d(m) \rightarrow 1$ as $m \rightarrow \infty$



The algorithm

Use a suitable version of a wave-front tracking algorithm (mainly from [Bressan \(2000\)](#) and [Amadori-Guerra \(2001\)](#)):

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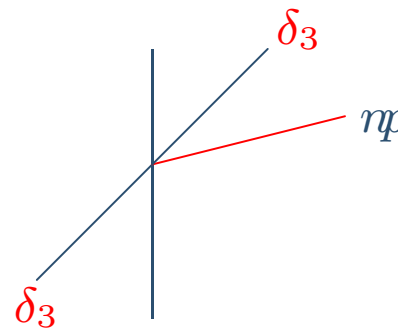
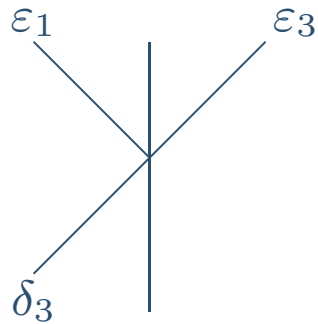
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The functionals

Introduce $\xi \geq 1$, $K \geq 0$ and define

$$L_\xi = \sum_{i=1,3, \text{ rar}} |\gamma_i| + \xi \sum_{i=1,3, \text{ sh}} |\gamma_i| + K_{np} \sum_{\gamma \in \mathcal{NP}} |\gamma|$$

$$Q = \sum_{\gamma_i, \delta_2 \text{ approaching}, i=1,3} |\gamma_i| |\delta_2|$$

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- After a suitable choice of the coefficients ξ and K (neither too small, nor too large), one finds

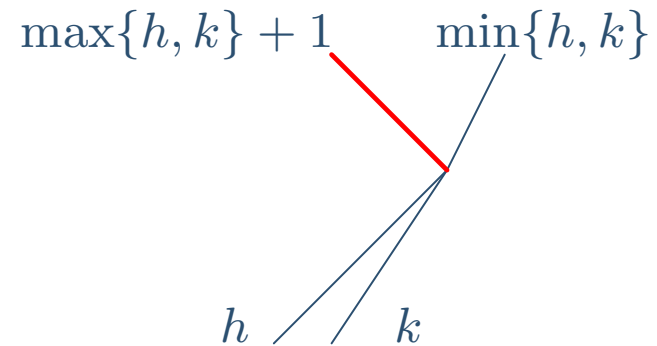
$$\Delta F(t) \leq 0 \quad \text{for all } t.$$

Convergence and consistence

- Prove that the number of interactions is **finite** in finite time.

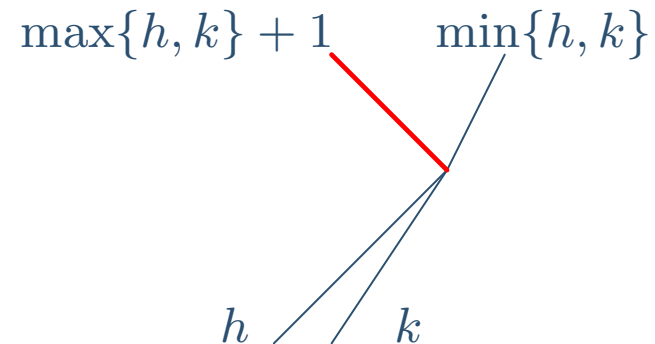
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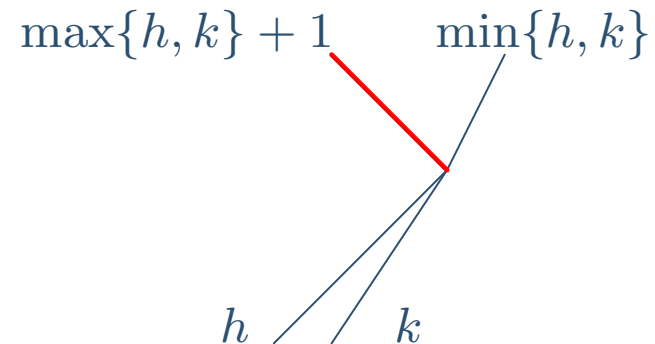
Lemma [A contraction property]

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- Pass to the limit by compactness.

The system with a reaction term

We come back to the complete system:

$$\text{(HS)} \quad \begin{cases} v_t - u_x & = 0 \\ u_t + p(v, \lambda)_x & = 0 \\ \lambda_t & = \frac{1}{\tau} g(p, \lambda), \quad g = (p - p_e)\lambda(\lambda - 1) \end{cases}$$

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Let $E = \{(v, u, \lambda) : g = 0\}$ be the set of equilibrium points of the source term. It consists of 3 subsets:

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- E_p , equilibrium pressure. Here the system reduces to

$$p = p_e, \quad u = \text{const.}, \quad \lambda = \lambda(x).$$

The case $\lambda \sim 0$

For $\tau > 0$ fixed, we focus on the case $\lambda \sim 0$. From the equation

$$\lambda_t = \frac{1}{\tau}(p - p_e)\lambda(\lambda - 1),$$

note that the sign of $(p - p_e)$ determines the behavior of the equation for λ : provided that

$$p - p_e \geq c > 0, \quad \lambda \leq \mu < 1$$

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[Dafermos & Hsiao, 1982]

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Theorem 2: For $\tau > 0$ fixed, assume that:

$$\inf v_o(x) > 0, \quad \inf p_o(x) > p_e$$

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and that

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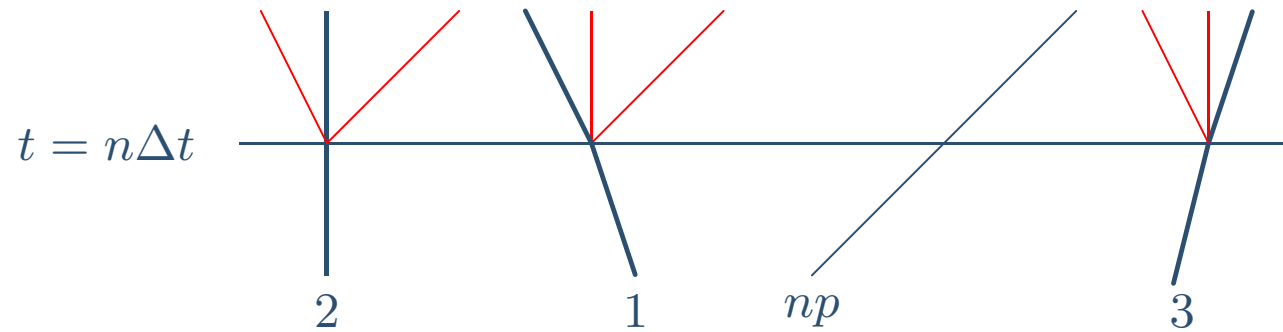
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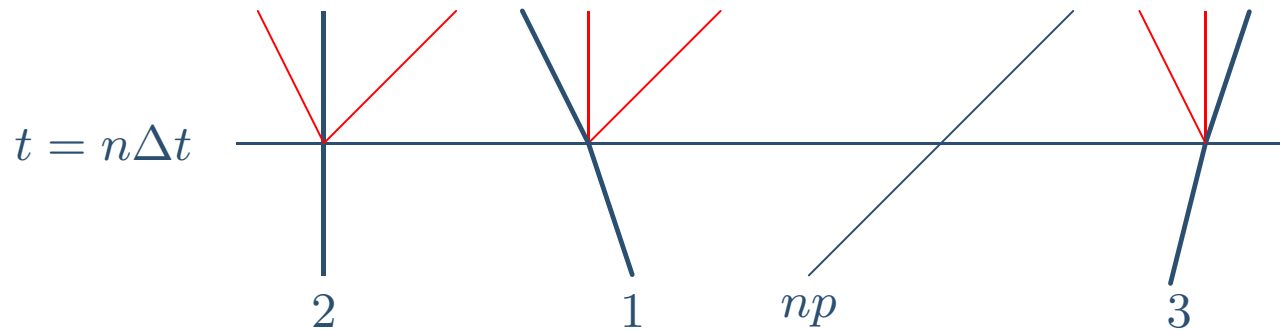
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Then the Cauchy problem for the system **(HS)** has a weak entropic solution (v, u, λ) defined for $t \geq 0$, with uniformly bounded total variation.

Applying the fractional step scheme...



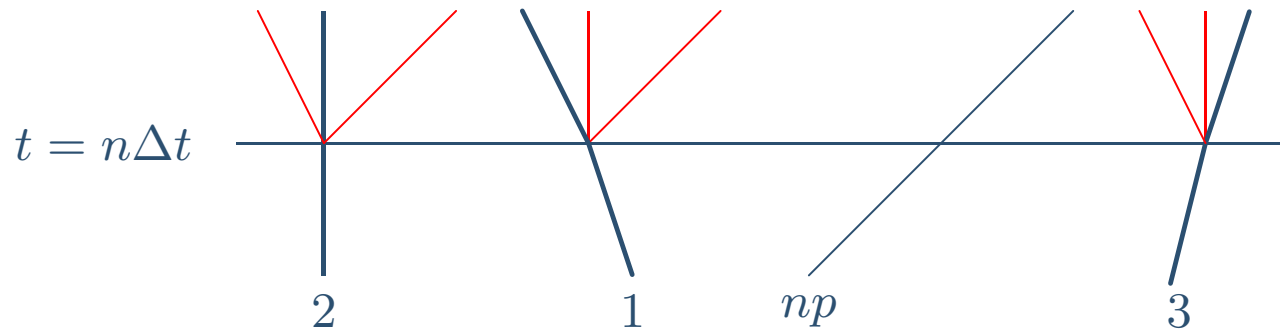
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■ For every $t > s \geq 0$, one has

$$\int_a^b |\lambda(x, t) - \lambda(x, s)| dx \leq L_\tau (t - s + \Delta t)$$

$$L_\tau = C_1 + \frac{C_2}{\tau} e^{-\frac{C_3 s}{\tau}}.$$

The relaxation limit

Theorem 3: For $\tau > 0$, consider the system **(HS)** and the initial data

$$(v, u, \lambda)(0, x) = (v_o^\tau(x), u_o^\tau(x), \lambda_o^\tau(x)),$$

satisfying the bounds of Theorem 2 uniformly with respect to τ . Assume that

$$v_o^\tau \rightarrow v_o, \quad u_o^\tau \rightarrow u_o \quad \text{in } L^1_{loc}(\mathbb{R}), \quad \text{as } \tau \rightarrow 0.$$

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$$\begin{aligned} \lambda^{\tau_n} &\rightarrow 0 && \text{in } L^1_{loc}(\mathbb{R} \times (0, \infty)) \\ (v^{\tau_n}, u^{\tau_n}) &\rightarrow (\tilde{v}, \tilde{u}) && \text{in } L^1_{loc}(\mathbb{R} \times [0, \infty)), \end{aligned}$$

where (\tilde{v}, \tilde{u}) is a weak solution for $t \geq 0$ to the Cauchy problem

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The relaxation limit: entropies

Given

$$\tilde{\eta}(v, u) = \frac{u^2}{2} - A(0) \log v, \quad \tilde{q}(v, u) = \frac{A(0)u}{v},$$

(entropy-entropy flux pair for the 2×2 system with $\lambda = 0$), then, for any smooth function ϕ

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■ Entropy inequality for $\tau > 0$:
$$\eta_t + q_x \leq \frac{1}{\tau} \underbrace{\eta_\lambda \cdot g(v, \lambda)}_{\leq 0}.$$

■ For a suitable choice of ϕ , the entropy is **dissipative w.r.t. the source term**. Hence one can pass to the limit $\tau_n \rightarrow 0$ and prove that the (\tilde{v}, \tilde{u}) satisfies the entropy inequality for the 2×2 system w.r.t. $\tilde{\eta}, \tilde{q}$.

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Shizuta-Kawashima condition is not satisfied at $p = p_e$: here

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where $G = (0, 0, g(v, \lambda))$ and $F = (-u, p, 0)$.

[Natalini-Hanouzet 2003]

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[Natalini-Hanouzet 2003]

- ◆ Weak solutions

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Thank you!!